

**TAREA 5**

**Alumno: Zepeda Rosales Ana Yadira**

**Carrera: Mecatronica**

**Grado/Grupo: 8 °A**

**Profesor: Moran Garabito Carlos Enrique**

**Asignatura: Cinemática de Robots**

**Periodo Cuatrimestral:** enero-abril 2019

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| ROBOT #4 | | | | |
| ESLABON | Ai-1 | Αi-1 | di | a |
| 1 | 0 | 0 | 0 |  |
| 2 | 0 | 90° | D1 | 0 |
| 3 | 0 | 0 | D2 | 0 |

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| ROBOT #5 | | | | |
| ESLABON | Ai-1 | Αi-1 | di | a |
| 1 | 0 | 0 | 0 |  |
| 2 | 0 | 0 | D2 | 180° |
| 3 | 90° | L3 | D3 | 90° |